

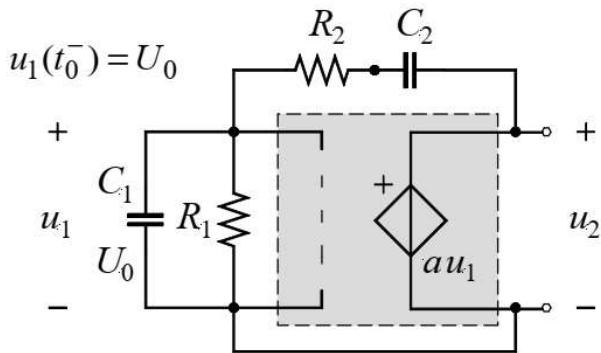
Одзив на почетне услове

Figure 1: Wien-bridge Oscillator

Вредности елемената електричног кола са слике су познате.

$$R_1 = R_2 = R, C_1 = C_2 = C, a = 3.$$

- (a) Колико главних пресека има граф кола?
- (б) Одредити једначине стања у матричном облику.
- (в) Одредити и нацртати напон u_2 за $t > t_0$, $t_0 = 0$.



Винов осцилатор (Wien bridge oscillator).

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(%i1) jednacine: [i1+i2+i3+i5=0,
                  -i4+i6+i7=0,
                  -i3+i4=0,
                  u1-u2=0,
                  u2-u5=0,
                  u5-u6-u4-u3=0,
                  u6-u7=0,
                  i1=C1 ·'diff(u1,t),
                  u2=R1 ·i2,
                  u3=R2 ·i3,
                  i4=C2 ·'diff(u4,t),
                  i5=0,
                  u6=a ·u5,
                  u7=R3 ·i7];
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(%o1) [i5+i3+i2+i1=0, i7+i6-i4=0, i4-i3=0, u1-u2=0, u2
      -u5=0, -u6+u5-u4-u3=0, u6-u7=0, i1=C1 ·(d/dt) u1, u2=R1 i2
      , u3=R2 i3, i4=C2 ·(d/dt) u4, i5=0, u6=a u5, u7=R3 i7]
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(%i2) jednacineDu1Du4: jednacine, 'diff(u1,t)=Du1, 'diff(u4,t)=Du4;
(%o2) [i5+i3+i2+i1=0, i7+i6-i4=0, i4-i3=0, u1-u2=0, u2
-u5=0, -u6+u5-u4-u3=0, u6-u7=0, i1=C1 Du1, u2=R1 i2, u3=
R2 i3, i4=C2 Du4, i5=0, u6=a u5, u7=R3 i7]

(%i3) JednacineIzvoda: eliminate(jednacineDu1Du4,
[i1, i2, i3, i4, i5, i6, i7, u2, u3, u5, u6, u7]);
(%o3) [R1 R2 (R2+R1) (u4+(-C2 Du4-C1 Du1) R1 a+C2 Du4 R2+
(C2 Du4+C1 Du1) R1), -(R2+R1)
(R1 u4+R1 a u1-R1 u1+R2 (-u1-C1 Du1 R1))]

(%i4) jednacineStanja: linsolve(JednacineIzvoda, [Du1, Du4]);
(%o4) [Du1=  $\frac{R1 u4 + R1 a u1 - R2 u1 - R1 u1}{C1 R1 R2}$ , Du4=  $-\frac{u4 + a u1 - u1}{C2 R2}$ ]

(%i5) jednacineDiff: jednacineStanja,
Du1='diff(u1, t),
Du4='diff(u4, t);
(%o5) [ $\frac{\frac{d}{dt} u1 = \frac{R1 u4 + R1 a u1 - R2 u1 - R1 u1}{C1 R1 R2}}{C2 R2}, \frac{d}{dt} u4 = -\frac{u4 + a u1 - u1}{C2 R2}]$ 

(%i6) zamene: [R1=R, R2=R, R3=R, C1=C, C2=C, a=3];
(%o6) [R1=R, R2=R, R3=R, C1=C, C2=C, a=3]

(%i7) jednacineDiffZamene:jednacineDiff, zamene, [u1=u1(t), u4=u4(t)];
(%o7) [ $\frac{\frac{d}{dt} u1(t) = \frac{R u4(t) + R u1(t)}{C R^2}}{C R}, \frac{d}{dt} u4(t) = -\frac{u4(t) + 2 u1(t)}{C R}]$ 

(%i8) atvalue(u1(t), t=0, U0);
(%o8) U0

(%i9) atvalue(u4(t), t=0, 0);
(%o9) 0

(%i10) assume(R>0, C>0);
(%o10) [R>0, C>0]
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(%i11) odziv: desolve(jednacineDiffZamene, [u1(t), u4(t)]), ratsimp;
(%o11) [u1(t)=U0 sin(  $\frac{t}{CR}$ ) + U0 cos(  $\frac{t}{CR}$ ), u4(t)=-2 U0
sin(  $\frac{t}{CR}$ )]
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(%i12) vrednosti: [R=1000, C=10⁻⁶, U0=10];

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(%o12) [R=1000, C= $\frac{1}{1000000}$ , U0=10]
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(%i13) uC1:u1(t), odziv, vrednosti;

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(%o13) 10 sin(1000 t) + 10 cos(1000 t)
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(%i14) wxplot2d([3·uC1], [t, 0, 0.02],
[xlabel, " t [s] "],
[ylabel, " u2 [V] "],
[legend, "Napon u2(t)"], grid2d)\$

